


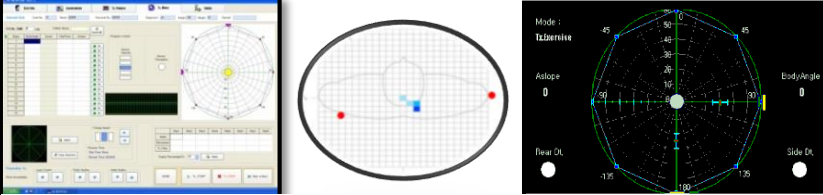

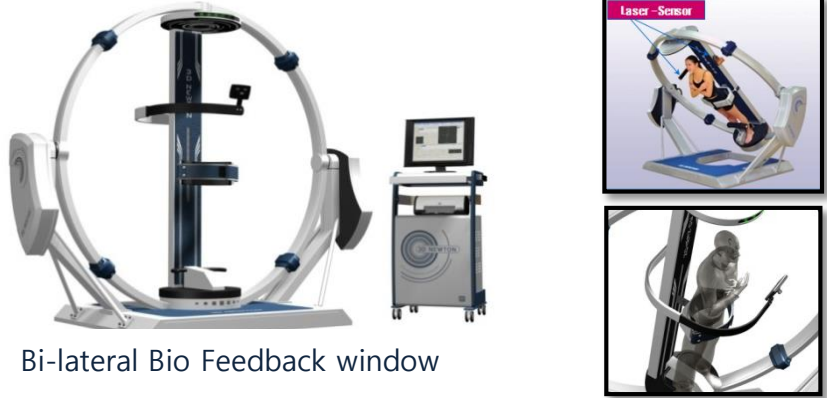

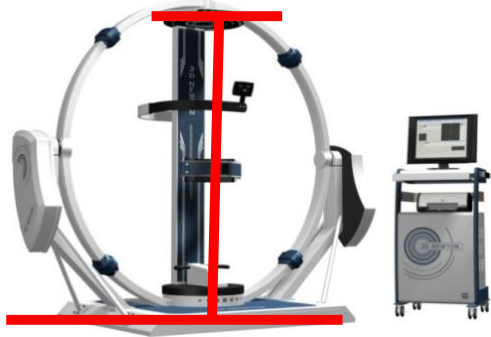


Comparison of Technologies of 3D Spatial Rotators

Name of Model	3D-CENTAUR	3D-NEWTON
<p>Equipments Display with Spatial Rotator Function</p>	 <p>Window to identify movement</p>	 <p>Bi-lateral Bio Feedback window</p>
<p>Patient Diagnosis Bio Feedback Automatic sensor</p>	 <ul style="list-style-type: none"> - No feedback sensor - Objective data not available - Verification of equipment, not on the patient 	 <ul style="list-style-type: none"> - Laser Dt measuring sensor up to 0.1mm - Bi-lateral type muscle training coaching system - Objective data on changes in 3D anti-gravity muscle
<p>Differential Technology</p>	<ul style="list-style-type: none"> - No patient monitoring function - Subjective data of curers - Subjective sthenometry - Unilateral adaption on the device 	<ul style="list-style-type: none"> - Objective data of the training results - Forecast of curing schedule after analysis on data of the sensors after analysis on data of the sensors - Real-time monitoring on physical movement by patient for better efficiency

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Name of Model	3D-CENTAUR	3D-NEWTON
<p>Equipments Display with Spatial Rotator Function</p>	 <p>Window to identify movement</p>	 <p>Bi-lateral Bio Feedback window</p>
<p>Motor maintenance</p>		
	<p>Structure is the load for motor is the floor only. Because of the structure, the replacement cycle of motor is short.</p>	<p>Structure is the load for motor is the floor and top. Because of the stable structure, the replacement cycle of motor is more long.</p>